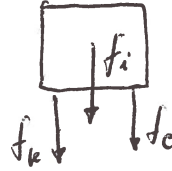
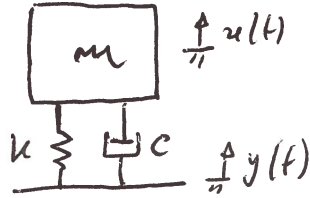


P1

a)

Assumptions
 $u > y$

$$f_i = m\ddot{u}$$

$$f_k = k(u-y)$$

$$f_c = c(\dot{u}-\dot{y})$$

$$m\ddot{u} + c(\dot{u}-\dot{y}) + k(u-y) = 0$$

$$m\ddot{u} + c\dot{u} + ku = c\dot{y} + ky$$

$$b) \quad T = \frac{1}{2} m \dot{u}^2 \quad V = \frac{1}{2} k(u-y)^2 \quad \mathcal{F} = \frac{1}{2} c(\dot{u}-\dot{y})^2$$

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{u}} \right) - \frac{\partial T}{\partial u} + \frac{\partial V}{\partial u} + \frac{\partial \mathcal{F}}{\partial \dot{u}} = 0$$

$$\downarrow \quad \quad \quad \downarrow \quad \quad \quad \downarrow$$

$$m\ddot{u} + k(u-y) + c(\dot{u}-\dot{y}) = 0$$

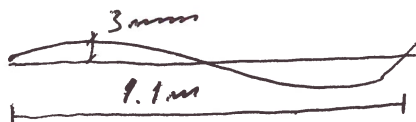
$$m\ddot{u} + c\dot{u} + ku = c\dot{y} + ky$$

$$c) \quad TR = \sqrt{\frac{k^2 + (\omega c)^2}{(k - \omega^2 m)^2 + (\omega c)^2}} = \sqrt{\frac{1 + (2\zeta\beta)^2}{(1 - \beta^2)^2 + (2\zeta\beta)^2}}$$

$$m = 500 \text{ kg} \quad k_f = 5.25 \times 10^6 \text{ N/m} \quad c_{eq} = 20 \times 10^3 \text{ Ns/m}$$

$$v = 61.2 \text{ km/h} = 17 \text{ m/s}$$

$$v = \frac{L}{T} \quad T = \frac{L}{v} = \frac{1.1}{17} = 0.0647 \text{ s}$$



$$T = \frac{2\pi}{\omega} \Rightarrow \omega = \frac{2\pi}{T} = \frac{2\pi}{0.0647} = 97.1 \text{ rad/s}$$

success zone
Your



$$TR = \sqrt{\frac{(5.25 \times 10^6)^2 + (97.1 \times 20 \times 10^3)^2}{(5.25 \times 10^6 - 97.1^2 \times 500)^2 + (97.1 \times 20 \times 10^3)^2}} = 2.78$$

A amplitude máxima de resposta é 2.78 vezes superior à amplitude imposta.

d) A amplitude de resposta será $2.78 \times 3 \times 10^{-3} = 8.34 \times 10^{-3}$ m
falte a deslocagem.

$$m\ddot{u} + c\dot{u} + ku = cy + ky$$

$$\begin{aligned} 500\ddot{u} + 20 \times 10^3 \dot{u} + 5.25 \times 10^6 u &= \\ &= 20 \times 10^3 \times 0.2913 \cos 97.1t + \\ &+ 5.25 \times 10^6 \times 3 \times 10^{-3} \sin 97.1t \end{aligned}$$

$$\begin{aligned} y &= Y \sin \omega t = 3 \times 10^{-3} \sin 97.1t \\ \dot{y} &= \omega Y \cos \omega t = \\ &= 97.1 \times 3 \times 10^{-3} \cos 97.1t \\ &= 0.2913 \cos 97.1t \end{aligned}$$

$$\begin{aligned} 500\ddot{u} + 20 \times 10^3 \dot{u} + 5.25 \times 10^6 u &= 5826 \cos 97.1t + 15750 \sin 97.1t \\ &= F \sin(97.1t + \varphi) = \\ &= F \sin 97.1t \cos \varphi + \\ &+ F \cos 97.1t \sin \varphi \end{aligned}$$

$$\begin{aligned} 5826 &= F \sin \varphi \\ 15750 &= F \cos \varphi \Rightarrow F = \sqrt{5826^2 + 15750^2} = 16793 \text{ N} \end{aligned}$$

$$\tan \varphi = 0.3699 \Rightarrow \varphi = 0.354 \text{ rad}$$

∴

$$500\ddot{u} + 20 \times 10^3 \dot{u} + 5.25 \times 10^6 u = 16793 \sin(97.1t + 0.354)$$

para $F \sin \omega t$ a resposta é $X \sin(\omega t - \alpha)$, c/ $\alpha = f^{-1} \frac{\omega c}{k - \omega^2 m}$

$$\alpha = f^{-1} \frac{97.1 \times 20 \times 10^3}{5.25 \times 10^6 - 97.1^2 \times 500} = 1.3016 \text{ rad}$$

mas $f(t)$ já tem uma deslocagem e prota, para $F \sin(\omega t + \varphi)$

a resposta será $X \sin(\omega t + \varphi - \alpha)$, i.e.

$$u(t) = 8.34 \times 10^{-3} \sin(97.1t + 0.354 - 1.3016)$$

$$u(t) = 8.34 \times 10^{-3} \sin(97.1t - 0.9476)$$

success zone
Your



A amplitude também se pode calcular a partir de

$$X = \frac{F}{\sqrt{(k - \omega^2 m)^2 + (c\omega)^2}} = \frac{16793}{\sqrt{(\underbrace{5.25 \times 10^6}_{k} - \underbrace{97.1^2 \times 500}_{\omega^2 m})^2 + (\underbrace{97.1 \times 20 \times 10^3}_{c\omega})^2}}$$

$$= \underline{\underline{8.34 \times 10^{-3} \text{ m}}}$$

e) Força transmitida pelo estudo: é através de k e c :

$$f_{tr}(t) = c(\dot{u} - \dot{y}) + k(u - y)$$

De eq. de equilíbrio, $m\ddot{u} + c(\dot{u} - \dot{y}) + k(u - y) = 0$

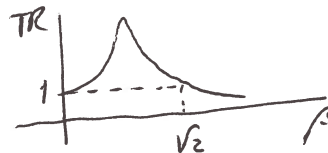
Donde $f_{tr}(t) = -m\ddot{u}(t) = +\omega^2 m u(t) =$

$$= 97.1^2 \times 500 \times 8.34 \times 10^{-3} \text{ sen}(97.1t - 0.9476) =$$

$$= 39316.5 \text{ sen}(97.1t - 0.9476)$$

O valor máximo é $F_{tr} = \underline{\underline{39316.5 \text{ N}}}$

f) $X \leq Y \Rightarrow \frac{X}{Y} \leq 1 \Rightarrow TR \leq 1 \Rightarrow \beta \geq \sqrt{2}$, qual seja seja o movimento.



$$\frac{\omega}{\omega_n} \geq \sqrt{2}$$

$$\omega \geq \sqrt{2} \omega_n$$

Como $v = \frac{L}{T} = \frac{L\omega}{2\pi}$, $\omega = \frac{2\pi}{L} v$

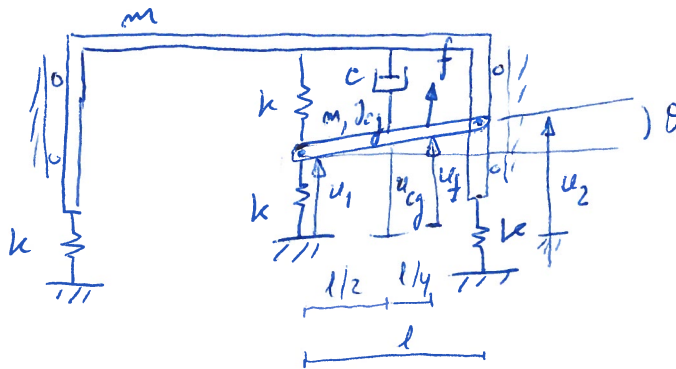
$$\frac{2\pi}{L} v \geq \sqrt{2} \omega_n \quad v \geq \frac{L}{2\pi} \sqrt{2} \omega_n \quad v \geq \frac{1.1}{2\pi} \sqrt{2} \cdot \sqrt{\frac{5.25 \times 10^6}{500}}$$

$$v \geq 25.37 \text{ m/s}$$

$$v \geq \underline{\underline{91.3 \text{ km/h}}}$$

success zone
Your

P2



$$i) T = \frac{1}{2} m \dot{u}_c^2 + \frac{1}{2} m \dot{u}_{cg}^2 + \frac{1}{2} J_{cg} \dot{\theta}^2$$

$$T = \frac{1}{2} m \dot{u}_c^2 + \frac{1}{2} m \left(\frac{\dot{u}_1 + \dot{u}_2}{2} \right)^2 + \frac{1}{2} \frac{1}{12} m l^2 \frac{(\dot{u}_2 - \dot{u}_1)^2}{l^2}$$

$$T = \frac{1}{2} m \dot{u}_c^2 + \frac{1}{2} \frac{m}{4} (\dot{u}_1 + \dot{u}_2)^2 + \frac{1}{2} \frac{1}{12} m (\dot{u}_2 - \dot{u}_1)^2$$

$$ii) V = \frac{1}{2} 2k u_2^2 + \frac{1}{2} k u_1^2 + \frac{1}{2} k (u_2 - u_1)^2$$

$$iii) F = \frac{1}{2} c (\dot{u}_c - \dot{u}_{cg})^2 = \frac{1}{2} \frac{c}{4} (\dot{u}_c - \dot{u}_1)^2$$

$$iv) \overline{\delta W} = f \delta u_f = Q_1 \delta u_1 + Q_2 \delta u_2$$

$$\overline{\delta W} = \frac{f}{4} \delta (u_1 + 3u_2) = Q_1 \delta u_1 + Q_2 \delta u_2$$

$$\frac{f}{4} \delta u_1 + \frac{3f}{4} \delta u_2 = Q_1 \delta u_1 + Q_2 \delta u_2$$

$$Q_1 = f/4, \quad Q_2 = 3f/4$$

$$b) \frac{d}{dt} \left(\frac{\partial T}{\partial \dot{u}_i} \right) - \frac{\partial T}{\partial u_i} + \frac{\partial V}{\partial u_i} + \frac{\partial F}{\partial \dot{u}_i} = Q_i \quad i = 1, 2$$

$$u_1: \frac{d}{dt} \left(\frac{\partial T}{\partial \dot{u}_1} \right) = \frac{m}{4} (\ddot{u}_1 + \ddot{u}_2) + \frac{1}{12} m (\ddot{u}_2 - \ddot{u}_1) (-1) = \frac{\partial T}{\partial u_1} = 0$$

$$= \frac{m}{8} \ddot{u}_1 + \frac{m}{6} \ddot{u}_2$$

$$\frac{\partial V}{\partial u_1} = k u_1 + k (u_2 - u_1) (-1) = 2k u_1 - k u_2$$

$$\frac{\partial F}{\partial \dot{u}_1} = \frac{c}{4} (\dot{u}_c - \dot{u}_1) (-1) = \frac{c}{4} (\dot{u}_1 - \dot{u}_2)$$

$$Q_1 = f/4$$

success zone
Your



$$\therefore \frac{m}{3} \ddot{u}_1 + \frac{m}{6} \ddot{u}_2 + \frac{c}{4} \dot{u}_1 - \frac{c}{4} \dot{u}_2 + 2ku_1 - ku_2 = f/4$$

$$u_2: \frac{d}{dt} \left(\frac{\partial T}{\partial \dot{u}_2} \right) = m \ddot{u}_2 + \frac{m}{4} (\dot{u}_1 + \dot{u}_2) + \frac{m}{12} (\ddot{u}_2 - \ddot{u}_1), \quad \frac{\partial T}{\partial u_2} = 0$$

$$= \frac{m}{6} \ddot{u}_1 + \frac{4}{3} m \ddot{u}_2$$

$$\frac{\partial V}{\partial u_2} = 2ku_2 + k(u_2 - u_1) = -ku_1 + 3ku_2$$

$$\frac{\partial F}{\partial \dot{u}_2} = \frac{c}{4} (\dot{u}_2 - \dot{u}_1) = -\frac{c}{4} \dot{u}_1 + \frac{c}{4} \dot{u}_2$$

$$Q_2 = 3f/4$$

$$\therefore \frac{m}{6} \ddot{u}_1 + \frac{4}{3} m \ddot{u}_2 - \frac{c}{4} \dot{u}_1 + \frac{c}{4} \dot{u}_2 - ku_1 + 3ku_2 = 3f/4$$

$$\begin{bmatrix} \frac{m}{3} & \frac{m}{6} \\ \frac{m}{6} & \frac{4}{3} m \end{bmatrix} \begin{Bmatrix} \ddot{u}_1 \\ \ddot{u}_2 \end{Bmatrix} + \begin{bmatrix} \frac{c}{4} & -\frac{c}{4} \\ -\frac{c}{4} & \frac{c}{4} \end{bmatrix} \begin{Bmatrix} \dot{u}_1 \\ \dot{u}_2 \end{Bmatrix} + \begin{bmatrix} 2k & -k \\ -k & 3k \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} = \begin{Bmatrix} f/4 \\ 3f/4 \end{Bmatrix}$$

$$c) \begin{bmatrix} 2k - \omega^2 \frac{m}{3} & -k - \omega^2 \frac{m}{6} \\ -k - \omega^2 \frac{m}{6} & 3k - \omega^2 \frac{4}{3} m \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

$$\left(2k - \omega^2 \frac{m}{3} \right) \left(3k - \omega^2 \frac{4}{3} m \right) - \left(-k - \omega^2 \frac{m}{6} \right)^2 = 0$$

$$6k^2 - \omega^2 km - \omega^2 \frac{8}{3} km + \omega^4 \frac{4}{9} m^2 - k^2 - \omega^4 \frac{m^2}{36} - \omega^2 \frac{1}{3} km = 0$$

$$\frac{15}{36} m^2 \omega^4 - 4km \omega^2 + 5k^2 = 0$$

$$\frac{5}{12} m^2 \omega^4 - 4km \omega^2 + 5k^2 = 0 \quad \omega^2 = \frac{4km \pm \sqrt{16k^2 m^2 - 4 \frac{25}{12} k^2 m^2}}{\frac{5}{6} m^2}$$

$$\omega^2 = \frac{4 \pm \sqrt{16 - \frac{25}{3}}}{5/6} \frac{k}{m} \quad k = 10^4 \text{ N/m}$$

$$\omega_1^2 = 14773.5 \text{ s}^{-2} \rightarrow \omega_1 = 121.55 \text{ rad/s} \quad m = 14 \text{ kg}$$

$$\omega_2^2 = 81226.5 \text{ s}^{-2} \rightarrow \omega_2 = 285 \text{ rad/s}$$

success zone
Your



Lodz University of Technology

1.^o modo:

$$(2k - \omega_1^2 \frac{m}{3}) u_1^{(1)} - (k + \omega_1^2 \frac{m}{6}) u_2^{(1)} = 0$$

$$(2 \times 10^4 - 14773.5 \times \frac{1}{3}) u_1^{(1)} - (10^4 + 14773.5 \times \frac{1}{6}) u_2^{(1)} = 0$$

$$u_1^{(1)} = 1 \Rightarrow u_2^{(1)} = 1.21 \rightarrow \begin{Bmatrix} 1 \\ 1.21 \end{Bmatrix}$$

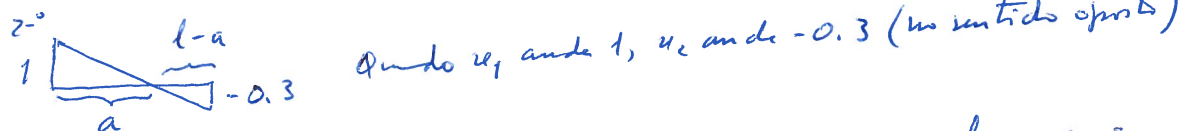
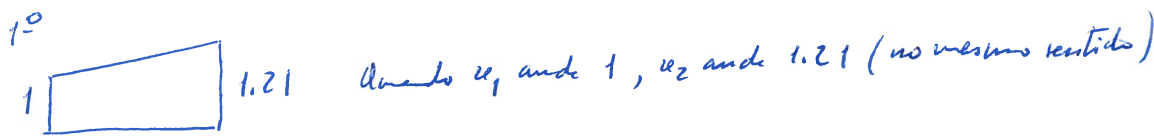
2.^o modo:

$$(2k - \omega_2^2 \frac{m}{3}) u_1^{(2)} - (k + \omega_2^2 \frac{m}{6}) u_2^{(2)} = 0$$

$$(2 \times 10^4 - 81226.5 \times \frac{1}{3}) u_1^{(2)} - (10^4 + 81226.5 \times \frac{1}{6}) u_2^{(2)} = 0$$

$$u_1^{(2)} = 1 \Rightarrow u_2^{(2)} = -0.3 \rightarrow \begin{Bmatrix} 1 \\ -0.3 \end{Bmatrix}$$

d)



$$\text{nodo: } \frac{1}{a} = \frac{0.3}{l-a} \Rightarrow l-a = 0.3a \Rightarrow l = 1.3a \Rightarrow a = \frac{l}{1.3} \approx 0.15 \text{ m}$$

O nodo está a \approx prox. 0.15m de u_1 .

$$f) \begin{bmatrix} 2 \times 10^4 - 150^2 \times \frac{1}{3} & -10^4 - 150^2 \times \frac{1}{6} \\ -10^4 - 150^2 \times \frac{1}{6} & 3 \times 10^4 - 150^2 \times \frac{4}{3} \end{bmatrix} \begin{Bmatrix} X_1 \\ X_2 \end{Bmatrix} = \begin{Bmatrix} 100/4 \\ 3 \times 100/4 \end{Bmatrix}$$

$$\begin{Bmatrix} X_1 \\ X_2 \end{Bmatrix} = \begin{Bmatrix} 5.45 \times 10^{-3} \text{ m} \\ 6.78 \times 10^{-3} \text{ m} \end{Bmatrix}$$

$$\begin{Bmatrix} u_1(t) = 5.45 \times 10^{-3} \text{ sen } 150t \\ u_2(t) = 6.78 \times 10^{-3} \text{ sen } 150t \end{Bmatrix}$$

success zone Your

P3

$$a) \quad AE u'(l, t) = -k u(l, t)$$

A condição de fronteira em $x=l$ é: quando a barra sofre um alongamento positivo, a mola exerce uma força no sentido negativo.



A força na face $x=l$ é $P = \sigma A$. A força da mola, F_k é $-k u(l, t)$. Portanto,

$$\sigma A = -k u(l, t)$$

$$\text{Como } \sigma = E \epsilon = E \frac{\partial u}{\partial x} = E u',$$

$$AE \frac{\partial u}{\partial x} \Big|_{x=l} = -k u(l, t)$$

$$AE u'(l, t) = -k u(l, t)$$

$$\text{Como } u(l, t) = \phi(l) T(t),$$

$$AE \phi'(l) T(t) = -k \phi(l) T(t)$$

$$\text{Para todo o tempo, } AE \phi'(l) = -k \phi(l)$$

$$b) \quad \text{Cond. de fronteira: } x=0 \Rightarrow u(0, t) = 0 \Rightarrow \phi(0) = 0$$

$$x=l \Rightarrow AE u'(l, t) = -k u(l, t)$$

$$\Rightarrow AE \phi'(l) = -k \phi(l)$$

$$\text{Como } \phi(x) = \tilde{A} \cos \frac{\omega}{c} x + \tilde{B} \sin \frac{\omega}{c} x, \quad c / c = \sqrt{\frac{E}{\rho}},$$

$$\text{de 1ª condição vem } 0 = \tilde{A} + 0 \Rightarrow \tilde{A} = 0$$

$$\phi'(x) = \tilde{B} \frac{\omega}{c} \cos \frac{\omega}{c} x$$

De 2ª condição,

$$AE \tilde{B} \frac{\omega}{c} \cos \frac{\omega}{c} l = -k \tilde{B} \sin \frac{\omega}{c} l$$

success zone
Your



$$AE \frac{\omega}{c} \cos \frac{\omega}{c} l = -k \sin \frac{\omega}{c} l$$

$$-\frac{AE}{k} \frac{\omega}{c} = \tan \frac{\omega}{c} l, \text{ ou } -\frac{AE}{kl} \frac{\omega}{c} l = \tan \frac{\omega}{c} l$$

$$\text{fazendo } \alpha = \frac{\omega}{c} l, \quad -\frac{AE}{kl} \alpha = \tan \alpha$$

$$\therefore \boxed{\frac{\tan \alpha}{\alpha} = -\frac{AE}{kl}} \text{ eq. de freqüências}$$

c) De eq. de freqüências, sai $\alpha_n = \frac{\omega_n l}{c}$, $n=1, \dots, \infty$

$$\text{Portanto, } \omega_n = \frac{\alpha_n c}{l}, \quad n=1, \dots, \infty$$

$$\text{Modos: } \phi^{(n)}(x) = B_n \sin \frac{\omega_n}{c} x$$

$$\phi^{(n)}(x) = B_n \sin \frac{\alpha_n}{l} x, \quad n=1, \dots, \infty$$

$$d) u^{(n)}(x,t) = \phi^{(n)}(x) T_n(t) = B_n \sin \frac{\alpha_n}{l} x (C_n \cos \omega_n t + D_n \sin \omega_n t)$$

Este é a resposta de cada modo.

A resposta total é a sobreposição das respostas de todos os modos:

$$u(x,t) = \sum_{n=1}^{\infty} \sin \frac{\alpha_n}{l} x (C_n \cos \omega_n t + D_n \sin \omega_n t)$$

em que C_n e D_n são calculados aplicando as condições iniciais de deslocamento e velocidade, $u(x,0)$, $\dot{u}(x,0)$, i.e., $u_0(x)$ e $\dot{u}_0(x)$.



P 4

a) $L_{p_1} = 10 \lg 5 + 120 - 10 \lg (2\pi \times 10^2) - 11 = 88 \text{ dB(A)}$
 $L_{p_2} = 10 \lg 2 + 120 - 10 \lg (2\pi \times 10^2) - 5 = 90 \text{ dB(A)}$
 $\Sigma E_i = 100 = \frac{\Delta t}{40} 10^{0.1 \times (88 - 67)} + \frac{\Delta t}{40} 10^{0.1 \times (90 - 67)}$
 $\Delta t = 12.3 \text{ h}$

b) $L_{p_1} = 116 - 10 \lg (2\pi r^2)$
 $L_{p_2} = 118 - 10 \lg (2\pi r^2)$
 $L_{p_T} = 87 = 10 \lg (10^{11.6 - \lg 2\pi r^2} + 10^{11.8 - \lg 2\pi r^2})$
 $10^{8.7} = \frac{10^{11.6} + 10^{11.8}}{2\pi r^2} \quad r = 18.1 \text{ m}$

c) $L_{p_1} = 86 \text{ dB(A)}$
 $L_{p_2} = 85 \text{ dB(A)} \Rightarrow 100 = \frac{\Delta t}{40} 10^{0.1(86-67)} + \frac{\Delta t}{40} 10^{0.1(85-67)}$
 $\Delta t = 28.1 \text{ h}$
Conseguir-se aumentar o tempo cerca de 2,3 vezes.

success zone
Your